Program: RFEM 5, RSTAB 8, RF-DYNAM Pro, DYNAM Pro

Category: Large Deformation Analysis, Dynamics, Member

Verification Example: 0119 – Spring with Clearance

# 0119 – Spring with Clearance

## Description

A single-mass system with clearance  $\delta$ , mass m and two springs  $k_1, k_2$  is initially deflected by  $u_{x0}$ . Determine the natural oscillations of the system – deflection, velocity and acceleration time course. The problem sketch is in **Figure 1** and it is described by the following set of parameters.

System Properties	Mass	т	10.000	kg
	Spring Stiffness	<i>k</i> <sub>1</sub>	100.000	N/mm
		k <sub>2</sub>	10.000	N/mm
	Clearance	δ	5.000	mm
	Initial Deflection	<i>u</i> <sub>x0</sub>	10.000	mm

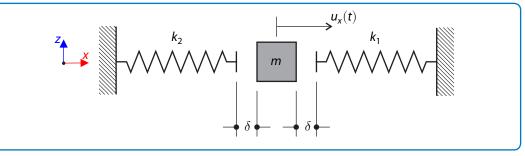


Figure 1: Problem Sketch

## **Analytical Solution**

This is a nonlinear problem due to the clearance and different sping stiffnesses. It can be described by means of three differential equations in three intervals

$m\ddot{u}_{x}+k_{1}(u_{x}-\delta)=0,$	$u_{x} \geq \delta$ ,	(119 – 1)
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$$m\ddot{u}_{x} = \mathbf{0}, \qquad u_{x} \in (-\delta, \delta), \tag{119-2}$$

$$m\ddot{u}_{x} + k_{2}(u_{x} + \delta) = 0, \qquad u_{x} \le -\delta, \qquad (119-3)$$

completed with the following initial conditions

$$u_{\rm x}(0) = u_{\rm x0} = 10.000 \,{\rm mm},$$
 (119 - 4)

$$\dot{u}_x(0) = 0.000 \text{ m/s.}$$
 (119 - 5)

The problem can be solved analytically in each interval. This solution is relatively complex, therefore a numeric solution (Runge–Kutta method) of the above mentioned differential equations is used. For the time course of the deflection, velocity and acceleration see **Figure 4**. The specific values at test time 0.25 s are listed below



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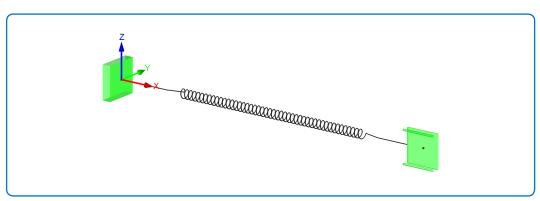
$u_x(0.25) = -20.434 \text{ [mm]},$	(119 – 6)
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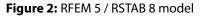
 $\dot{u}_x(0.25) = -0.098 \,[\text{m/s}],$  (119 - 7)

 $\ddot{u}_x(0.25) = 15.434 \,[\text{m/s}^2].$  (119 – 8)

## **RFEM 5 and RSTAB 8 Settings**

- Modeled in RFEM 5.17.01 and RSTAB 8.17.01
- Spring member with diagram is used, see Figure 2 and Figure 3





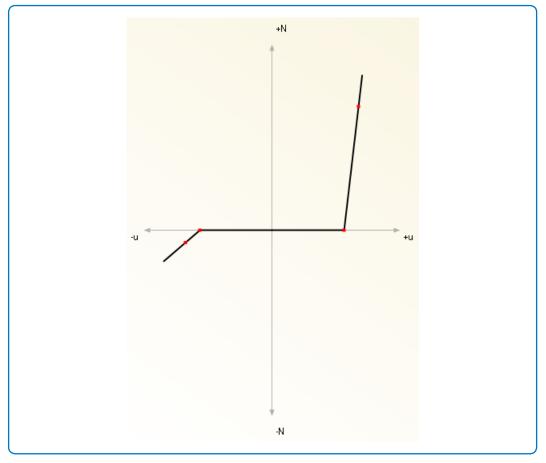


Figure 3: Diagram of the spring member in RFEM 5 / RSTAB 8

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## Results

Structure Files	Program	Solution Method
0119.01	RFEM 5 – RF-DYNAM Pro	Explicit analysis
0119.02	RFEM 5 – RF-DYNAM Pro	Nonlinear implicit Newmark analysis
0119.03	RSTAB 8 – DYNAM Pro	Explicit analysis

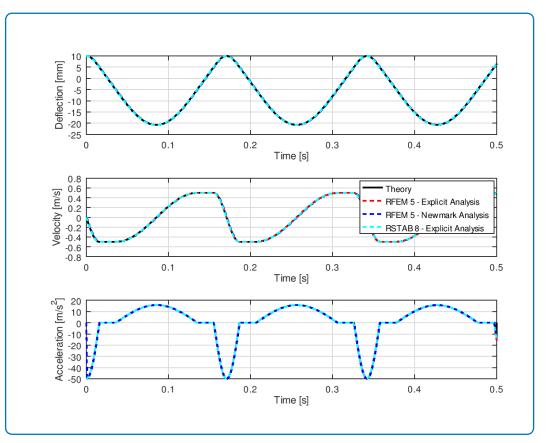


Figure 4: Results comparison

Model	Reference Solution	RFEM 5 / RSTAB 8	
	<i>u<sub>x</sub></i> [mm]	<i>u<sub>x</sub></i> [mm]	Ratio [-]
RFEM 5, Explicit Analysis		-20.486	1.003
RFEM 5, Nonlinear Newmark Analysis	-20.434	-20.432	1.000
RSTAB 8, Explicit Analysis		-20.474	1.002

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Model	Reference Solution	RFEM 5 / RSTAB 8	
	<i>ü<sub>x</sub></i> [m/s]	<i>ü<sub>x</sub></i> [m/s]	Ratio [-]
RFEM 5, Explicit Analysis		-0.097	0.990
RFEM 5, Nonlinear Newmark Analysis	-0.098	-0.106	1.082
RSTAB 8, Explicit Analysis		-0.097	0.990

Model	Reference Solution	RFEM 5 / RSTAB 8	
	ü <sub>x</sub> [mm/s²]	ü <sub>x</sub> [mm/s²]	Ratio [-]
RFEM 5, Explicit Analysis		15.485	1.003
RFEM 5, Nonlinear Newmark Analysis	15.434	15.432	1.000
RSTAB 8, Explicit Analysis		15.473	1.003