Program: RFEM 5, RSTAB 8, RF-DYNAM Pro, DYNAM Pro

Category: Geometrically Linear Analysis, Isotropic Linear Elasticity, Member, Dynamics

Verification Example: 0114 - Impulse Applied to Simply Supported Beam

# 0114 - Impulse Applied to Simply Supported Beam

### **Description**

A given force  $F_z$  is applied for a short period of time  $\Delta t$  at the mid-span of a simply supported beam. Considering only small deformation theory and assuming that the mass m of the beam is concentrated at its mid-span, determine its maximum deflection  $u_{\rm max}$ .

Material	Elastic	Modulus of Elasticity	Е	50.000	GPa
		Poisson's Ratio	ν	0.500	_
Geometry	Beam	Width	W	0.100	m
		Height	h	0.100	m
		Length	L	1.000	m
Load	Force	Value	F <sub>z</sub>	100.000	kN
		Period of Time	$\Delta t$	0.010	S
Mass	Concentrated	Mid-span	m	25000.000	kg

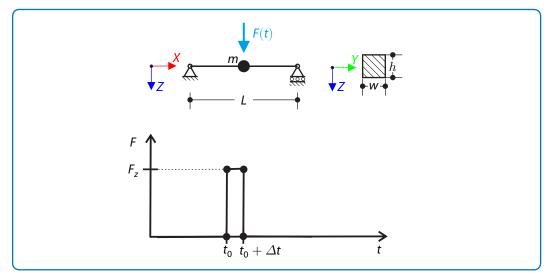


Figure 1: Problem Sketch

#### **Analytical Solution**

For the loading to be classified as an impulse, it has to be verified that it is applied for a time interval  $\Delta t$  shorter than one quarter of the natural period  $T=2\pi/\omega$  of the structure, where  $\omega$  is the angular frequency of the beam

$$\omega = \sqrt{\frac{k}{m}} \tag{114-1}$$

#### Verification Example: 0114 - Impulse Applied to Simply Supported Beam

and k is its bending stiffness defined as a multiplicative inverse of the maximum deflection  $u_1$  of the beam subjected to the unit mid-span force

$$k = \frac{1}{u_1} = \frac{48EI}{L^3} = \frac{4Ewh^3}{L^3}$$
 (114 – 2)

where  $I = \frac{wh^3}{12}$  is the second moment of beam cross-section area. Therefore, it indeed holds that

0.010 s = 
$$\Delta t < \frac{T}{4} = \frac{\pi}{2\omega} = \frac{\pi}{4} \sqrt{\frac{L^3 m}{Ewh^3}} \approx 0.055$$
 s (114 – 3)

and the load can be classified as an impulse J

$$J = \int_{t_0}^{t_0 + \Delta t} F_z(t) dt \tag{114-4}$$

The beam can be simplified as a single-degree-of-freedom system, the behavior of which is described by the second-order differential equation of undamped motion

$$m\frac{d^2u}{dt^2}(t) + ku(t) = 0 {(114-5)}$$

which admits the general solution

$$u(t) = A\cos(\omega t) + B\sin(\omega t) \tag{114-6}$$

with unknown real parameters A and B. Setting the end of impulse as the beginning of beam motion, i.e.,  $t_0 + \Delta t = 0$ , the following initial conditions apply

$$u(t_0 + \Delta t) = 0 \tag{114-7}$$

$$\frac{\mathrm{d}u}{\mathrm{d}t}(t_0) = 0\tag{114-8}$$

Knowing that the impulse J can be defined as the change in momentum

$$J = m\frac{\mathrm{d}u}{\mathrm{d}t}(t_0 + \Delta t) - m\frac{\mathrm{d}u}{\mathrm{d}t}(t_0)$$
 (114 – 9)

the coefficients A and B can be determined from (114 - 5) and (114 - 9)

$$u(0) = 0 \qquad \Rightarrow A = 0 \tag{114-10}$$

$$u(0) = 0$$
  $\Rightarrow A = 0$  (114 - 10)  
 $\frac{du}{dt}(0) = \frac{J}{m}$   $\Rightarrow B = \frac{J}{m\omega}$  (114 - 11)

#### Verification Example: 0114 – Impulse Applied to Simply Supported Beam

Hence, (114 - 6) reads as

$$u(t) = \frac{J}{m\omega} \sin \omega t \tag{114-12}$$

and the formula for the maximal displacement  $u_{\mathrm{max}}$  can be easily derived

$$u_{\text{max}} = \frac{J}{m\omega} \tag{114-13}$$

## **RFEM 5 and RSTAB 8 Settings**

- Modelled in version RFEM 5.07.07 and RSTAB 8.07.05
- Geometrically linear analysis is considered
- Shear stiffness of members is deactivated
- Mass is considered to act in the Z-direction
- Root of characteristic polynomial is used as solving method

#### **Results**

Structure File	Program			
0114.01	RF-DYNAM Pro			
0114.02	DYNAM Pro			

As can be seen from the table below, good agreement of the analytical result with the numerical output was achieved

Analytical Solution	RF-DYNAM Pro		DYNAM Pro	
u <sub>max</sub> [mm]	u <sub>max</sub> [mm]	Ratio [-]	u <sub>max</sub> [mm]	Ratio [-]
1.414	1.410	0.997	1.410	0.997